# Classification of $C^*$ -algebras, flow equivalence of shift spaces, and graph and Leavitt path algebras

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# Content









# Outline



2 Wiiliams' theorem

3 Franks' theorem



# Key definitions

Let  $\mathfrak a$  be a finite set and equip  $\mathfrak a^{\mathbb Z}$  with the product topology based on the discrete topology on  $\mathfrak a.$ 

#### Definition

A shift space is a subset X of  $\mathfrak{a}^{\mathbb{Z}}$  which is closed and closed under the shift map

$$\sigma: \mathfrak{a}^{\mathbb{Z}} \to \mathfrak{a}^{\mathbb{Z}} \qquad \sigma((x_i)) = (x_{i+1})$$

#### Definition

When  $E = (E^0, E^1, r, s)$  is a finite graph,  $X_E$  denotes the *edge* shift

$$\mathsf{X}_E = \{ (e_i) \in (E^1)^{\mathbb{Z}} \mid r(e_i) = s(e_{i+1}) \}$$

It is customary and convenient to think of  $E = E_A$  as defined by an adjacency matrix A and abbreviate  $X_A = X_{E_A}$ .

# Essential graphs

Obviously, sinks and sources do not contribute to the edge shifts, so we try to avoid these.

#### Definition

E is essential if it contains no sinks and no sources.

1	2	1
2	10	5
3	104	55
4	3044	1918



## Definition

X and Y are *conjugate*, written  $X\simeq Y,$  if there exists a bijection  $\varphi:X\to Y$  which is a homeomorphism and satisfies

 $\sigma\circ\varphi=\varphi\circ\sigma$ 

The *shifts of finite type* (SFTs) are the shift spaces conjugate to edge shifts.

# Easy invariants

#### Definition

A shift space X is *irreducible* when for some  $x \in X$ ,

$$\{\sigma^n(x) \mid n \in \mathbb{N}\}\$$

is dense in X.

#### Observation

Let X and Y be conjugate shift spaces.

- If X is finite, so is Y.
- If X is irreducible, so is Y.

Note that  $X_A$  is finite precisely when  $E_A$  is a union of disjoint cycles, and that  $X_A$  is irreducible precisely when  $E_A$  is strongly connected.

## Flow equivalence

Associated to any shift space there is a  $\ensuremath{\text{suspension flow}}$  given by product topology on

$$SX = \frac{X \times \mathbb{R}}{(x,t) \sim (\sigma(x), t+1)}$$

#### Definition

X and Y are flow equivalent (written  $X \sim_{\text{FE}} Y$ ) when SX and SY are homeomorphic in a way preserving direction in  $\mathbb{R}$ .

# Symbol expansion

Fix  $a \in \mathfrak{a}$  and  $\star \notin \mathfrak{a}$  and define  $\eta : \mathfrak{a}^{\mathbb{Z}} \to (\mathfrak{a} \cup \{\star\})^{\mathbb{Z}}$  as the map inserting a  $\star$  after each a:

 $\cdots babbbaba \cdots \mapsto \cdots ba \star bbba \star ba \star \cdots$ 

### Definition

The " $a\mapsto a\star$  " symbol expansion of a shift space X is the shift space

$$X_{a\mapsto a\star} = \eta(X) \cup \sigma(\eta(X)).$$

## Lemma

 $X \sim_{\mathrm{FE}} X_{a \to a \star}$ 

## Proof idea

$$\varphi([x,t]) = \begin{cases} [\eta(x), 2t] & x_0 = a, t \in [0, 1/2] \\ [\sigma(\eta(x)), 2t - 1] & x_0 = a, t \in [1/2, 1] \\ [\eta(x), t] & x_0 \neq a \end{cases}$$

## Key result

## Theorem (Parry-Sullivan)

Flow equivalence is the coarsest equivalence relation containing conjugacy and  $X \sim X_{a \to a \star}$ 

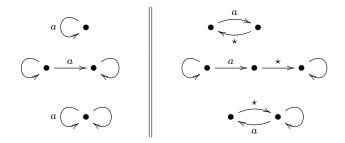
#### Observation

Let  $X \sim_{\text{FE}} Y$ .

- If X is finite, so is Y.
- If X is irreducible, so is Y.



Note how symbol expansion takes the form of *edge expansion* for edge shifts:



# Outline



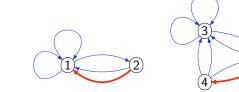






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# State splitting



$$\begin{bmatrix} 2 & 1 \\ 2 & 0 \end{bmatrix} = \begin{bmatrix} 2 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix} \qquad \begin{bmatrix} 2 & 0 & 1 \\ 2 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}$$

# Key result

## Definition

Two matrices A and B are elementary equivalent if there exist (possibly rectangular) matrices D, E with entries in  $\mathbb{N}_0$  so that

DE = A ED = B

#### Definition

*Strong shift equivalence* is the coarsest equivalence relation containing elemenary equivalence.

### Theorem (Williams)

Two edge shifts  $X_A$  and  $X_B$  given by essential matrices are conjugate precisely when A and B are strong shift equivalent.

# Key result

#### Theorem (Williams)

Conjugacy is coarsest equivalence relation on the set of edge shifts by essential graphs containing in-splitting, out-splitting and isomorphism of graphs.

#### Corollary

Flow equivalence is the coarsest equivalence relation on the set of edge shifts by essential graphs containing

- in-splitting
- out-splitting
- edge expansion
- isomorphism of graphs

# Outline



2 Wiiliams' theorem

3 Franks' theorem



### Definition

Let A be the adjacency matrix of an essential graph with n vertices. The  ${\it Bowen-Franks}$  invariant of A is the pair

$$BF(A) = [\mathbb{Z}^n / (\mathrm{Id} - A)\mathbb{Z}^n, \mathrm{sgn}(\det(\mathrm{Id} - A))]$$

#### Observation

When  $X_A \sim_{FE} X_B$ , BF(A) = BF(B)

# Flow classification of SFTs

## Theorem (Franks)

Let  $X_A$  and  $X_B$  be two irreducible and infinite SFTs given by graphs with essential adjacency matrices A and B, respectively. The following conditions are equivalent.

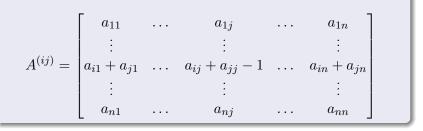
(i) 
$$X_A \sim_{\text{FE}} X_B$$

(ii)  $BF(A) \simeq BF(B)$ 

# Proof idea

#### Lemma (Basic move)

When  $A \ge 0$  with  $a_{ij} > 0$  we have that  $X_A \sim_{FE} X_{A^{(ij)}}$  where



# Step 1 Outspli

lit to go
$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \rightarrow \begin{bmatrix} 0 & 0 & 1 \\ a_{11} & a_{11} & a_{12} - 1 \\ a_{21} & a_{21} & a_{22} \end{bmatrix}$$

## Step 2

Insplit to go

$$\begin{bmatrix} 0 & 0 & 1 \\ a_{11} & a_{11} & a_{12} - 1 \\ a_{21} & a_{21} & a_{22} \end{bmatrix} \rightarrow \begin{bmatrix} 0 & 0 & 1 & 0 \\ a_{11} & a_{11} & 0 & a_{12} - 1 \\ a_{21} & a_{21} & 0 & a_{22} \\ a_{21} & a_{21} & 0 & a_{22} \end{bmatrix}$$

## Step 3

## Symbol reduce to go

$$\begin{bmatrix} 0 & 0 & 1 & 0 \\ a_{11} & a_{11} & 0 & a_{12} - 1 \\ a_{21} & a_{21} & 0 & a_{22} \\ a_{21} & a_{21} & 0 & a_{22} \end{bmatrix} \rightarrow \begin{bmatrix} a_{11} & a_{11} & a_{12} - 1 \\ a_{21} & a_{21} & a_{22} \\ a_{21} & a_{21} & a_{22} \end{bmatrix}$$

## Step 4

## Out-amalgamate to go

$$\begin{bmatrix} a_{11} & a_{11} & a_{12} - 1 \\ a_{21} & a_{21} & a_{22} \\ a_{21} & a_{21} & a_{22} \end{bmatrix} \rightarrow \begin{bmatrix} a_{11} + a_{21} & a_{12} + a_{22} - 1 \\ a_{21} & a_{22} \end{bmatrix}$$

For any  $A\geq 0$  there is a  $B\geq 0$  such that

$$X_A \sim_{\scriptscriptstyle \mathrm{FE}} X_{I+B}$$

#### Proof

If all  $a_{jj} > 0$  we are done. If not, employ that

$$A^{(ij)} = \begin{bmatrix} a_{11} & \dots & a_{1j} & \dots & a_{1n} \\ \vdots & & \vdots & & \vdots \\ a_{i1} + a_{j1} & \dots & a_{ij} - 1 & \dots & a_{in} + a_{jn} \\ \vdots & & \vdots & & \vdots \\ a_{n1} & \dots & a_{nj} & \dots & a_{nn} \end{bmatrix}$$

to create a zero column, which may then be deleted.

If a row or column addition takes an irreducible matrix  $B\geq 0$  to  $B'\geq 0,$  we have

$$X_{I+B} \sim_{\scriptscriptstyle{\mathrm{FE}}} X_{I+B'}$$

#### Proof

Suppose row 2 of B is added to row 1 to create  $B^{\prime}.$  The first row of  $I+B^{\prime}$  is

$$\begin{bmatrix} 1 + b_{11} + b_{21} & b_{12} + b_{22} & b_{13} + b_{23} & \ldots \end{bmatrix}$$

and the first two rows of  ${\cal I}+{\cal B}$  are

$$\begin{bmatrix} 1+b_{11} & b_{12} & b_{13} & \dots \\ b_{21} & 1+b_{22} & b_{23} & \dots \end{bmatrix}$$

Note how this coincides with "basic move" when  $b_{12} > 0$ . In general, use irreducibility.

Let an irreducible matrix  $B \ge 0$  be of size  $n \times n$  with n > 1. Then

$$X_{I+B} \sim_{\scriptscriptstyle \mathrm{FE}} X_{I+C}$$

where we may assume that C > 0 of any size  $m \ge n$ .

#### Proof

We may keep adding rows until all entries are  $\geq N$  for any N > 0. New rows may be added as required by state splitting as soon as the entries are sufficiently large.

When C > 0 we have  $X_{I+C} \sim X_{I+D}$  where the first column of D is identically d, with

$$d = \gcd\{c_{ij}\} = \gcd\{d_{ij}\}$$

#### Proof

Subsequent "column prepared row subtractions" and "row prepared column subtractions".

## Standard form 1

When C>0 is a given  $n\times n\text{-matrix}$  with  $\mathbb{Z}^n/C\mathbb{Z}^n=\sum_{i=1}^n\mathbb{Z}/d_i\mathbb{Z}$  where

$$d_1 \mid d_2 \mid \cdots \mid d_n$$

and  $\det(-C) = (-1)^n \det(C) < 0$  we have that  $X_{I+C} \sim X_{I+D}$  where

$$D = \begin{bmatrix} 0 & \dots & 0 & d_n \\ d_1 & 0 & & 0 & 0 \\ 0 & d_2 & & 0 & 0 \\ & \ddots & & \vdots \\ 0 & \dots & d_{n-1} & 0 \end{bmatrix}$$

## Standard form 2

When C>0 is a given  $n\times n\text{-matrix}$  with  $\mathbb{Z}^n/C\mathbb{Z}^n=\sum_{i=1}^n\mathbb{Z}/d_i\mathbb{Z}$  where

$$d_1 \mid d_2 \mid \cdots \mid d_n$$

and  $\det(-C) = (-1)^n \det(C) > 0$  we have that  $X_{I+C} \sim X_{I+D}$  where

$$D = \begin{bmatrix} 0 & \dots & d_{n-1} & d_{n-1} \\ d_1 & 0 & 0 & 0 \\ 0 & d_2 & 0 & 0 \\ & \ddots & \vdots & \vdots \\ 0 & \dots & d_{n-1} & d_{n-1} + d_n \end{bmatrix}$$

## Standard form 3

When C>0 is a given  $n\times n\text{-matrix}$  with  $\mathbb{Z}^n/C\mathbb{Z}^n=\sum_{i=1}^n\mathbb{Z}/d_i\mathbb{Z}$  where

$$d_1 \mid d_2 \mid \cdots \mid d_n$$

and  $\operatorname{rank}(C) = k < n$  we have that  $X_{I+C} \sim X_{I+D}$  where

$$D = \begin{bmatrix} 0 & \dots & 0 & d_k & \dots & d_k \\ d_1 & 0 & 0 & 0 & \dots & 0 \\ 0 & d_2 & & 0 & & 0 \\ & & \ddots & \vdots & \vdots & & \\ & & d_{k-1} & 0 & \dots & 0 \\ 0 & & \dots & 0 & d_k & \dots & d_k \\ \vdots & & & \vdots & \vdots & & \vdots \\ 0 & & \dots & 0 & d_k & \dots & d_k \end{bmatrix}$$

# Outline



2 Wiiliams' theorem

3 Franks' theorem



We call a non-irreducible shift space reducible. Any reducible shift space can be analyzed into irreducible components which in turn define a partially ordered set where one component  $C_1$  dominates another component  $C_2$  when there is a path from some vertex in  $C_1$  to some vertex in  $C_2$ . When  $X = X_A$ , we color those vertices that correspond to irreducible components that are single cycles and arrive at a colored partially ordered set  $\mathcal{P}_A$ .

## 1 5

### Observation

When  $X_A \sim_{FE} X_B$ ,  $\mathcal{P}_A \simeq \mathcal{P}_B$ .

We can even associate the Bowen-Franks invariant to all the points in  $\mathcal{P}_A$ !

# Recall irreducible case

#### Proposition

If a row or column addition takes an irreducible matrix  $B\geq 0$  to  $B'\geq 0,$  we have

$$\mathsf{X}_{I+B}\sim_{\scriptscriptstyle\mathrm{FE}}\mathsf{X}_{I+B'}$$

#### Proof

Suppose row 2 of B is added to row 1 to create  $B^{\prime}.$  The first row of  $I+B^{\prime}$  is

$$\begin{bmatrix} 1 + b_{11} + b_{21} & b_{12} + b_{22} & b_{13} + b_{23} & \ldots \end{bmatrix}$$

and the first two rows of  $\boldsymbol{I}+\boldsymbol{B}$  are

$$\begin{bmatrix} 1+b_{11} & b_{12} & b_{13} & \dots \\ b_{21} & 1+b_{22} & b_{23} & \dots \end{bmatrix}$$

Note how this coincides with "basic move" when  $b_{12} > 0...$ 

If the addition of row or column j to row or column i takes an irreducible matrix  $B\geq 0$  to  $B'\geq 0,$  we have

$$\mathsf{X}_{I+B}\sim_{\scriptscriptstyle\mathrm{FE}}\mathsf{X}_{I+B'}$$

when  $B_{ij} > 0$ 

# Recall irreducible case

Assume that  $B,B^\prime$  are irreducible matrices both of size n. Then the following are equivalent

**③** There exist SL matrices U, V with

UBV = B'

### Theorem (Boyle-Huang, Boyle)

Let  $X_A$  and  $X_B$  be reducible edge shifts with isomorphic colored partial order given by their irreducible components. Then  $X_A \sim_{FE} X_B$  in a way preserving the given isomorphism precisely when there exist block SL matrices U, V such that

U(I - A')V = I - B'

where  $X_{A'}\sim_{\rm FE} X_A$  and  $X_{B'}\sim_{\rm FE} X_B$  are prepared on the form

- Any irreducible component which is a single cycle has only one vertex
- Any irreducible component which is not a single cycle has positive entries and has at least two more vertices than there are summands in the Bowen-Franks group