Søren Eilers eilers@math.ku.dk

Department of Mathematical Sciences University of Copenhagen

> Lecture 3 May 13, 2015

Content

- FE versus ME
- 2 K-theory
- The gauge simple case
- 4 Geometric classification
- Matsumoto/Matui

Geometric classification

Let X_A and X_B be reducible edge shifts with isomorphic colored partial order given by their irreducible components. Then $X_A \sim_{FE} X_B$ in a way preserving the given isomorphism precisely when there exist block SL matrices U,V such that

$$U(I - A')V = I - B'$$

where $X_{A'} \sim_{FE} X_A$ and $X_{B'} \sim_{FE} X_B$ are prepared on the form

- Any irreducible component which is a single cycle has only one vertex
- Any irreducible component which is not a single cycle has positive entries and at least two more vertices than there are summands in the Bowen-Franks group

FE versus ME K-theory The gauge simple case Geometric classification Matsumoto/Matui

Key remarks

- Flow equivalence, i.e. existence of such SL block matrices, is decidable, but not practically so.
- The proof constructively replaces U and V by a sequence of row/column additions/subtractions.
- A Franks' standard form is not useful in the general case.

Outline

- FE versus ME

$$C(S^{1}) \oplus \mathbb{C} \qquad \bullet \qquad \bullet \qquad \qquad \bullet$$

$$C(S^{1}) \oplus C(S^{1}) \qquad \bullet \qquad \bullet \qquad \qquad \bullet$$

$$M_{2}(C(S^{1})) \qquad \bullet \qquad \bullet \qquad \qquad \bullet$$

$$M_{2}(C(S^{1})) \qquad \bullet \leftarrow \bullet \qquad \qquad \bullet$$

$$? \qquad \bigcirc \bullet \longrightarrow \bullet \bigcirc$$

$$\bullet \qquad \quad \mathbb{C} \oplus \mathbb{C}$$

$$\bullet \longrightarrow \bullet \qquad M_2(\mathbb{C})$$

$$\bigcirc \bullet \longrightarrow \bullet \qquad \mathcal{T}$$

$$\bigcirc \bullet \bigcirc \bullet \bigcirc \circ \bigcirc \circ$$

$$\bullet \bigcirc \circ \bigcirc \circ \bigcirc \circ$$

$$?$$

Theorem (Cuntz/Krieger)

If E and F are essential and finite graphs, then

$$X_E \sim_{FE} X_F \Longrightarrow C^*(E) \sim_{ME} C^*(F)$$

Let E be an essential and finite graph. If E^{\sharp} arises from E by an out-splitting, we have

Geometric classification

$$C^*(E^\sharp) \simeq C^*(E)$$

We outsplit E by partitioning

$$s^{-1}(v) = \mathcal{E}_v^1 \sqcup \mathcal{E}_v^2 \sqcup \cdots \sqcup \mathcal{E}_v^{n(v)}$$

Then we have

$$\begin{array}{lcl} (E^{\sharp})^{0} & = & \{v^{i} \mid v \in E^{0}, i = 1, \ldots, n(v)\} \\ (E^{\sharp})^{1} & = & \{e^{i} \mid e \in E^{1}, i = 1, \ldots, n(r(e))\} \\ r(e^{i}) & = & r(e)^{i} \\ s(e^{i}) & = & s(e)^{\mathcal{E}(e)} \text{ when } e \in \mathcal{E}_{s(e)}^{\mathcal{E}(e)} \end{array}$$

Geometric classification

FE versus ME

Let E be an essential and finite graph. If E^{\sharp} arises from E by an out-spliting, we have

$$C^*(E^\sharp) \simeq C^*(E)$$

Proof

We define $\varphi: C^*(E) \to C^*(E^{\sharp})$ by

$$\varphi(p_v) = \sum_{i=1}^{n(v)} p_{v^i} \qquad \varphi(s_e) = \sum_{i=1}^{n(r(e))} s_{e^i}$$

The map is easily seen to be surjective, and it is injective by the GIUT.

Proposition

FE versus ME

Let E be an essential and finite graph. If E_{t} arises from E by an out-spliting, we have

$$C^*(E_{\sharp}) \sim_{\mathrm{ME}} C^*(E)$$

We in-split E by partitioning

$$r^{-1}(v) = \mathcal{E}_1^v \sqcup \mathcal{E}_2^v \sqcup \cdots \sqcup \mathcal{E}_{n(v)}^v$$

Then we have

$$(E_{\sharp})^{0} = \{v_{i} \mid v \in E^{0}, i = 1, \dots, n(v)\}$$

$$(E_{\sharp})^{1} = \{e_{i} \mid e \in E^{1}, i = 1, \dots, n(s(e))\}$$

$$r(e_{i}) = r(e)_{\mathcal{E}(e)} \text{ when } e \in \mathcal{E}_{\mathcal{E}(e)}^{r(e)}$$

$$s(e_{i}) = s(e)_{i}$$

Let E be an essential and finite graph. If E_{t} arises from E by an in-spliting, we have

$$C^*(E_{\sharp}) \sim_{\mathrm{ME}} C^*(E)$$

Proof

We define $\varphi: C^*(E) \to C^*(E_{\dagger})$ by

$$\varphi(p_v) = p_{v_1}$$
 $\varphi(s_e) = \sum_{f \in s^{-1}(r(e))} s_{e_1} s_{f_{\mathcal{E}(e)}} s_{f_1}^*$

As before, it is injective by the GIUT, and the image is $p_{\rm tt}C^*(E_{\rm tt})p_{\rm tt}$ with

$$p_{\sharp} = \sum_{v \in F_0} p_{v_1}$$

When $\mathfrak A$ and $\mathfrak B$ are separable C^* -algebras, the following are equivalent

- 2 There exists a C^* -algebra $\mathfrak D$ and orthogonal full projections $p, q \in M(\mathfrak{D})$ with

$$p\mathfrak{D}p \simeq \mathfrak{A} \qquad q\mathfrak{D}q \simeq \mathfrak{B}$$

Geometric classification

There exists an $\mathfrak{A} - \mathfrak{B}$ imprimitivity bimodule

We say that ${\mathfrak A}$ and ${\mathfrak B}$ are *Morita equivalent* and write ${\mathfrak A}\sim_{\scriptscriptstyle{\mathrm{ME}}}{\mathfrak B}$ in this case. Note all of

$$\mathbb{C}, M_2(\mathbb{C}), M_3(\mathbb{C}), \ldots, \mathbb{K}$$

are Morita equivalent.

Geometric classification

FE versus ME

Let E be an essential and finite graph. If \hat{E} arises from E by an edge expansion, we have

$$C^*(E) \sim_{\mathrm{ME}} C^*(\widetilde{E})$$

Extending the edge f gives the graph

$$\begin{split} (\widetilde{E})^0 &= \{v^0 \mid v \in E^0\} \cup \{w_1\} \\ (\widetilde{E})^1 &= \{e^0 \mid e \in E^1 \setminus \{f\}\} \cup \{f^0, f^1\} \\ r(e^0) &= r(e)^0 \text{ when } e \neq f \\ s(e^0) &= s(e)^0 \text{ when } e \neq f \\ s(f^0) &= s(f)^0 \\ r(f^0) &= s(f^1) = w^1 \\ r(f^1) &= r(f)^0 \end{split}$$

Proposition

FE versus ME

Let E be an essential and finite graph. If \widetilde{E} arises from E by an edge expansion, we have

$$C^*(E) \sim_{\mathrm{ME}} C^*(\widetilde{E})$$

Proof

We define $\varphi: C^*(E) \to C^*(\widetilde{E})$ by

$$\varphi(p_v) = p_{v^0} \qquad \varphi(s_e) = s_{e^0} \qquad \varphi(s_f) = s_{f^0} s_{f^1}$$

When we define $\beta_z \in \operatorname{Aut}(C^*(\widetilde{E}))$ by

$$eta_z(p_{v^0}) = p_{v^0} \qquad eta_z(p_{w^0}) = p_{w^0} \ eta_z(s_{e^0}) = z s_{e^0} \qquad eta_z(s_{f^0}) = z s_{f^0} \qquad eta_z(s_{f^1}) = s_{f^1}$$

we get $\beta_z \circ \varphi = \varphi \circ \gamma_z$, so we can again conclude that it is injective by the GIUT. The image is $(1-p_{m^1})C^*(\widetilde{E})(1-p_{m^1})$.

	Morita	*-	Gauge
	equivalence	isomorphism	invariance
Out-splitting			
In-splitting		-	√
Edge expansion		-	-

Flow equivalence is the coarsest equivalence relation on the set of edge shifts by essential graphs containing in-splitting, out-splitting. edge expansion, isomorphism of graphs.

Theorem (Cuntz/Krieger)

If E and F are essential and finite graphs, then

$$X_E \sim_{FE} X_F \Longrightarrow C^*(E) \sim_{ME} C^*(F)$$

$C(S^1)\oplus \mathbb{C}$ • •	$ullet$ $ullet$ $oldsymbol{\mathbb{C}}\oplus oldsymbol{\mathbb{C}}$	
$C(S^1) \oplus C(S^1)$ • • •	$\bullet \longrightarrow \bullet \qquad M_2(\mathbb{C})$	
$M_2(C(S^1))$ • • •		
$M_2(C(S^1)) \bigcirc \bullet \longleftarrow \bullet$	$\bigcirc \bullet \bigcirc \bullet \bigcirc \mathcal{O}_2$	

Outline

- 1 FE versus ME
- 2 K-theory
- 3 The gauge simple case
- 4 Geometric classification
- Matsumoto/Matu

$$\mathsf{A}_E = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & \infty & 0 \end{bmatrix}$$

$$\mathsf{A}_E^{\bullet} = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \end{bmatrix} \quad \mathsf{A}_E^{\circ} = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & \infty & 0 \end{bmatrix}$$

Geometric classification

A subtler invariant

K-theory for C^* -algebras is invariant for Morita equivalence.

Formulas

With A_E^{\bullet} the regular part of the adjacency matrix of E and I^{\bullet} the corresponding part of the identity matrix, we have

$$K_0(C^*(E)) = \operatorname{cok}(I^{\bullet} - \mathsf{A}_E^{\bullet})^t$$

 $K_1(C^*(E)) = \ker(I^{\bullet} - \mathsf{A}_E^{\bullet})^t$

Key observation

 $K_0(C^*(E))$ coincides with the Bowen-Franks group when E is essential and finite!

Geometric classification

$$\mathsf{A}_{E}^{\bullet} = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \end{bmatrix} \quad \mathsf{A}_{E}^{\circ} = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & \infty & 0 \end{bmatrix}$$

$$I = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \quad I^{\bullet} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} \quad I^{\circ} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$(I^{\bullet} - \mathsf{A}_{E}^{\bullet})^{t} = \begin{bmatrix} -1 & 0 \\ 1 & -1 \\ 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 0 \\ 0 & -1 \\ 0 & 0 & 0 \end{bmatrix}$$

Outline

- The gauge simple case

Definition

FE versus ME

A Kirchberg algebra is

- simple
- purely infinite
- nuclear
- separable

Definition

A C^* -algebra is said to be AF (approximately finite) if it is the inductive limit of finite-dimensional C^* -algebras.

FE versus ME K-theory The gauge simple case Geometric classification Matsumoto/Matui

Trichotomy

Theorem

If a graph C^{st} -algebra has no non-trivial gauge invariant ideals, it is either

- an AF algebra;
- a Kirchberg algebra; or
- **3** $C(\mathbb{T}) \otimes \mathbb{K}(\mathcal{H})$ for some Hilbert space \mathcal{H} .

The first case occurs when the graph has no cycles; the second when one vertex supports several cycles.

When $\mathfrak A$ and $\mathfrak B$ are AF algebras, then

$$K_0(\mathfrak{A}) \simeq K_0(\mathfrak{B}) \Longleftrightarrow \mathfrak{A} \sim_{\scriptscriptstyle{\mathrm{ME}}} \mathfrak{B}$$

Theorem (Kirchberg-Phillips)

When $\mathfrak A$ and $\mathfrak B$ are Kirchberg algebras with the UCT, then

$$K_*(\mathfrak{A}) \simeq K_*(\mathfrak{B}) \Longleftrightarrow \mathfrak{A} \sim_{\mathrm{ME}} \mathfrak{B}$$

Geometric classification

If two graph C^* -algebras $C^*(E)$ and $C^*(F)$ have no non-trivial gauge invariant ideals, we have

$$K_*(C^*(E)) \simeq K_*(C^*(F)) \Longleftrightarrow C^*(E) \sim_{\text{ME}} C^*(F)$$

One needs to use the order of K_0 to distinguish between the three cases in the trichotomy, which is easy since

- **1** \mathfrak{A} an AF algebra: $K_0(\mathfrak{A})_+ \neq K_0(\mathfrak{A}), K_1(\mathfrak{A}) = 0.$
- **2** \mathfrak{A} a Kirchberg algebra: $K_0(\mathfrak{A})_+ = K_0(\mathfrak{A})$
- 3 $\mathfrak{A} = C(\mathbb{T}) \otimes \mathbb{K}(H)$: $K_0(\mathfrak{A})_+ \neq K_0(\mathfrak{A})$, $K_1(\mathfrak{A}) \neq 0$.

Consider the two graphs E, F given by



We have

$$\mathbb{Z}/(I-\mathsf{A}_E)\mathbb{Z}=0=\mathbb{Z}^2/(I-\mathsf{A}_F)\mathbb{Z}^2$$

but

$$\det(I - \mathsf{A}_E) = -1 \neq 1 = \det(I - \mathsf{A}_F).$$

Observation (Cuntz/Rørdam)

 $E \not\sim_{\text{FE}} F$, yet $C^*(E) \sim_{\text{ME}} C^*(F)$.

Historical remark/motivation

The classification of simple graph C^* -algebras associated to essential and finite graphs by Rørdam predates the Kirchberg-Phillips theorem and provided several clues to its proof.

Outline

- 4 Geometric classification

Moves

Move (S)

Remove a regular source, as



Move (R)

Reduce a configuration with a transitional regular vertex, as

$$\bullet \bigcirc \uparrow \star \longrightarrow \bullet \rightsquigarrow \bullet \bigcirc \uparrow \bullet$$

or



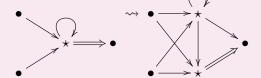
Moves

Move (I) Insplit at regular vertex

Geometric classification

FE versus ME

Outsplit at any vertex (at most one group of edges infinite)



Move (C)

"Cuntz splice" on a vertex supporting two cycles



Geometric classification

Let E and F be graphs with finitely many elements so that $C^*(E)$ and $C^*(F)$ are gauge simple. Then the following are equivalent

- **1** $C^*(E) \sim_{ME} C^*(F)$
- There is a finite sequence of moves of type

and their inverses, leading from E to F.

Outline

- 1 FE versus ME
- 2 K-theory
- 3 The gauge simple case
- 4 Geometric classification
- Matsumoto/Matui

A MASA $\mathfrak D$ in a C^* -algebra $\mathfrak A$ is a maximal abelian subalgebra (commutative and not contained in any larger such subalgebra). We reserve the notation $\mathfrak{D} \hookrightarrow \mathfrak{A}$ for this situation.

Example

FE versus ME

Consider the elements in $\mathbb{K}(H)$ as infinite matrices given by some orthonormal basis for H. Then the entries in each diagonal matrix must tend to zero, and we get

$$c_0 \hookrightarrow \mathbb{K}$$

Example

With

$$\mathfrak{D}_E = C^*(s_\alpha s_\alpha^* \mid \alpha \text{ a path in } E) \subset C^*(E)$$

we get when every cycle has an exit that

$$\mathfrak{D}_E \hookrightarrow C^*(E)$$

Let now E again be essential and finite. In this case we have in fact $\mathfrak{D}_E \simeq C(\mathsf{X}_E)$.

	Morita	*-	Gauge	D -
	equiv.	isom.	invariance	preserving
Out-splitting				
In-splitting		-		√
Edge expansion		-	-	
Cuntz splice		-	-	-

Observation

When $X_E \sim_{FE} X_F$, we have

$$C^*(E) \otimes \mathbb{K} \xrightarrow{\simeq} C^*(F) \otimes \mathbb{K}$$

$$\downarrow \qquad \qquad \downarrow \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \downarrow \qquad \qquad \downarrow \qquad \qquad \downarrow \qquad \qquad \downarrow$$

Geometric classification

With E and F presenting irreducible SFTs, the following are equivalent

(i)
$$X_E \sim_{FE} X_F$$

(ii)
$$C^*(E) \otimes \mathbb{K} \xrightarrow{\simeq} C^*(F) \otimes \mathbb{K}$$

$$\downarrow \qquad \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \downarrow \qquad \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \downarrow \qquad \qquad \downarrow \qquad \qquad \downarrow \qquad \qquad$$

By the results already described, we "just" need to prove that (ii) implies that $\operatorname{sgn} \det(1 - A_E) = \operatorname{sgn} \det(1 - A_F)$. This goes via a result of Boyle/Handelman on ordered cohomology.